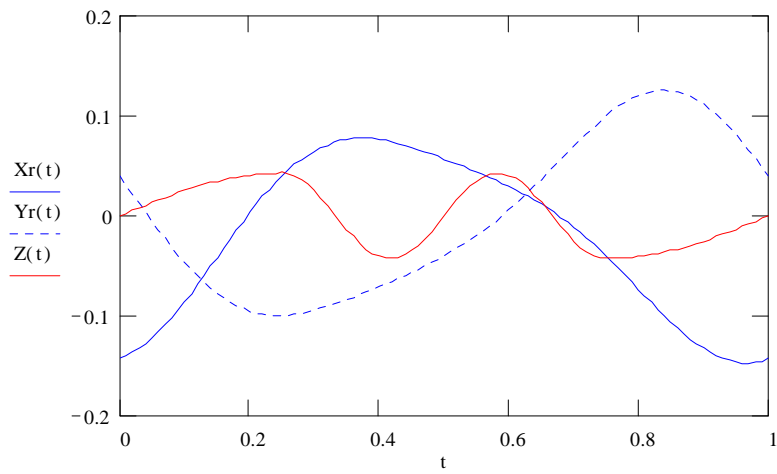
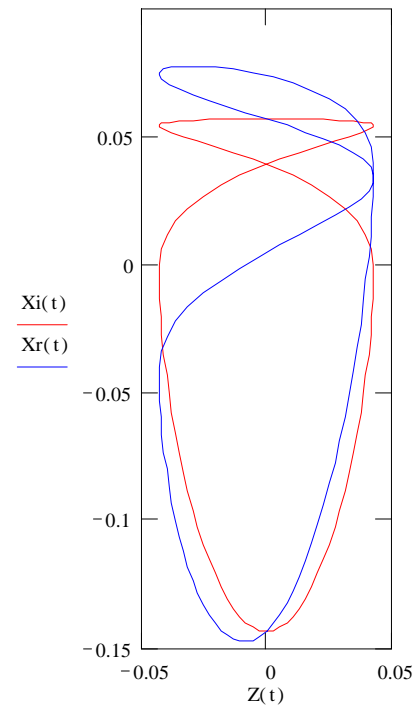
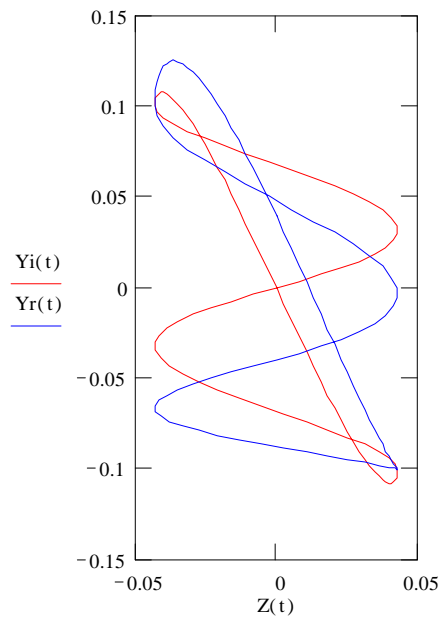
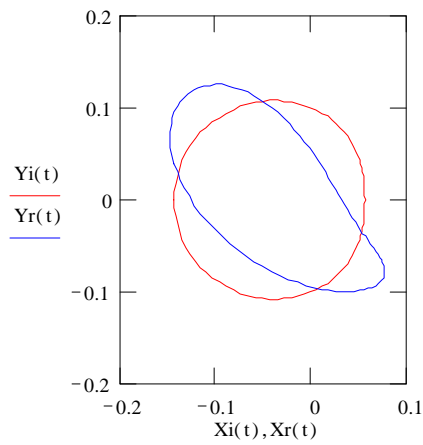
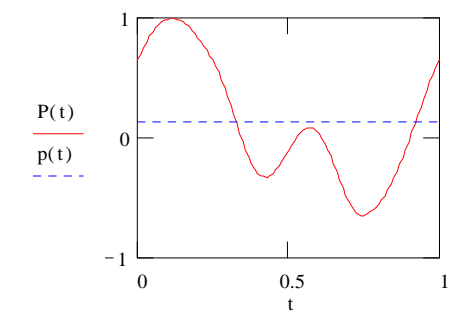


$F := -1$      $R := -0.1$     $r := -0.043$     $h := 0.04$     $\Omega := 2\pi$     $\omega := -\Omega$     $t := 0, 0.01..1$     **Alles SI-Einheiten**     $q(t) := \text{if}(\cos(\Omega \cdot t) > 0, 1, -1)$   
 $X_i(t) := (R + r \cdot \cos(\omega \cdot t)) \cdot \cos(\Omega \cdot t)$      $Y_i(t) := (R + r \cdot \cos(\omega \cdot t)) \cdot \sin(\Omega \cdot t)$      $Z(t) := r \cdot \sin(2 \cdot \omega \cdot q(t) \cdot t - \omega \cdot t)$   
 $X_r(t) := (R + r \cdot \cos(\omega \cdot t)) \cdot \cos(\Omega \cdot t) + h \cdot \sin(\Omega \cdot t)$      $Y_r(t) := (R + r \cdot \cos(\omega \cdot t)) \cdot \sin(\Omega \cdot t) + h \cdot \cos(\Omega \cdot t)$



$X_r(0) = -0.143$   
 $Y_r(0) = 0.04$   
 $Z(0) = 0$

$P(t) := F \cdot ((X_r(t) + Y_r(t)) \cdot \Omega + Z(t) \cdot \omega)$      $p(t) := \int_0^1 P(t) dt$   
 $p(0) = 0.135$



$P_{xr}(t) := F \cdot X_r(t) \cdot \Omega$      $P(t) := F \cdot \int_0^1 (X_r(t) \cdot \Omega) dt$

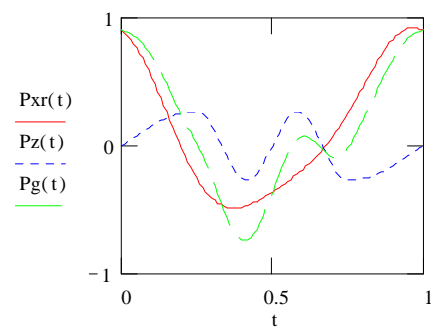
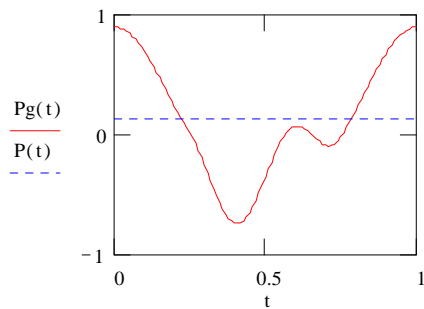
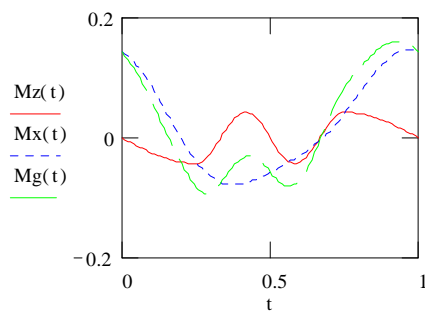
$P(1) = 0.13509$     **Watt pro Arm**  
 $\frac{P(1)}{10^3} = 1.351 \cdot 10^{-4}$

$P_z(t) := F \cdot Z(t) \cdot \omega$      $P_z(0.25) = 0.27$

$M_x(t) := F \cdot X_r(t)$   
 $M_z(t) := F \cdot Z(t)$   
 $M_g(t) := M_x(t) + M_z(t)$

$P_g(t) := M_x(t) \cdot \Omega + M_z(t) \cdot \omega$   
 $P_g(0) = 0.898$

$P_{zg}(t) := F \cdot \int_0^1 Z(t) dt \cdot \omega$      $P_{zg}(1) = 0$



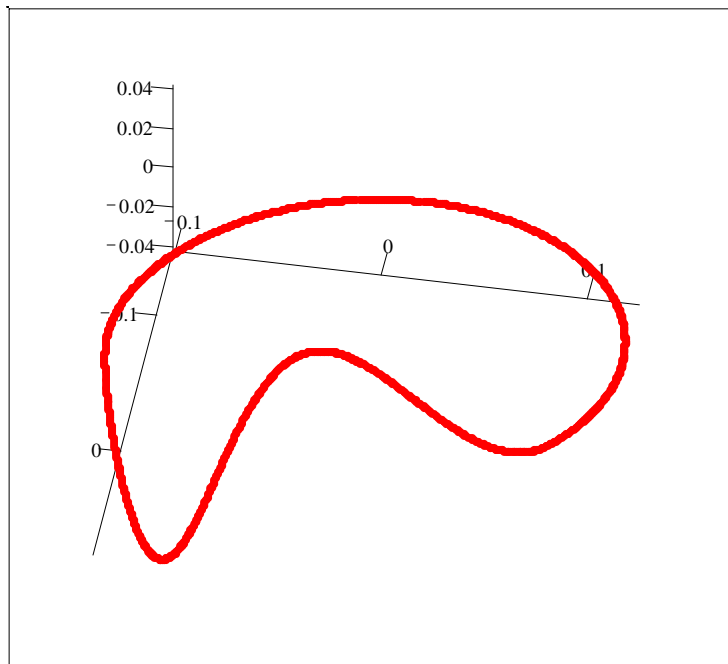
n := 1000    i := 0.. n - 1    ω := -Ω

$$X_i := \left( R + r \cdot \cos\left(\omega \cdot \frac{i}{n}\right) \right) \cdot \cos\left(\Omega \cdot \frac{i}{n}\right) + h \cdot \sin\left(\Omega \cdot \frac{i}{n}\right)$$

$$Y_i := \left( R + r \cdot \cos\left(\omega \cdot \frac{i}{n}\right) \right) \cdot \sin\left(\Omega \cdot \frac{i}{n}\right) + h \cdot \cos\left(\Omega \cdot \frac{i}{n}\right)$$

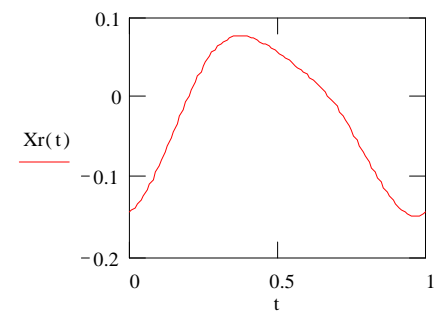
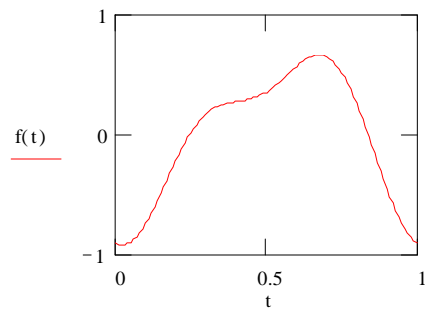
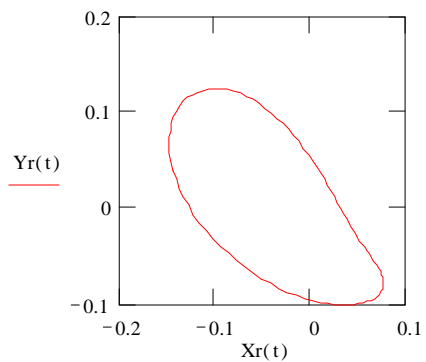
$$q_i := \text{if}\left(\cos\left(\Omega \cdot \frac{i}{n}\right) > 0, 1, -1\right)$$

$$Z_i := r \cdot \sin\left(2 \cdot \omega \cdot q_i \cdot \frac{i}{n} - \omega \cdot \frac{i}{n}\right)$$



X, Y, Z

$$f(t) := \frac{d}{dt} Y_r(t)$$



```
T1 :=
n ← 0
t ← 0.3
while n < 6
  |
  |   d Yr(t)
  |   dt
  |   t ← t - -----
  |   d² Yr(t)
  |   dt²
  |   n ← n + 1
  |
t ← t
```

T1 = 0.245

Yr(T1) = -0.1

```
T2 :=
n ← 0
t ← 0.8
while n < 6
  |
  |   d Yr(t)
  |   dt
  |   t ← t - -----
  |   d² Yr(t)
  |   dt²
  |   n ← n + 1
  |
t ← t
```

T2 = 0.839

Yr(T2) = 0.125

```
T01 :=
n ← 0
t ← 0.1
while n < 6
  |
  |   Xr(t)
  |   dt
  |   t ← t - -----
  |   d² Xr(t)
  |   dt²
  |   n ← n + 1
  |
t ← t
```

T01 = 0.196

$$L01 := \int_{T02}^{T01} Xr(t) dt$$

L01 =  $-7.531 \cdot 10^{-3}$

```
T02 :=
n ← 0
t ← 0.7
while n < 6
  |
  |   Xr(t)
  |   dt
  |   t ← t - -----
  |   d² Xr(t)
  |   dt²
  |   n ← n + 1
  |
t ← t
```

T02 = 0.677

$$Lpos := \int_{T1}^{T02} Xr(t) dt \quad Lpos = 0.015$$

$$Lneg := \int_{T01}^{T1+1} Xr(t) dt \quad Lneg = -0.037$$

Lges := Lpos + Lneg

Lges = -0.022

Pges := F · Lges · Ω

Pges = 0.135